

# EB260F.IR-2R092.VUMJN.01024L

Programmable incremental encoder with zero pulse + IO-Link for condition monitoring

Article number: 11732179

## Overview

- LowHarmonics auto-calibration eliminates temperature and mechanical signal errors
- For precise control of position and speed
- Smart condition monitoring with Airgap Monitor
- Bearingless design for compact integration
- Immune to dust, moisture, shaft currents and wear
- Intuitive parameterization of resolution, interface and speed monitor
- Magnetic rotor not included in delivery


*Picture similar*

## Technical data

### Technical data - electrical ratings

Voltage supply	4.5...30 VDC 18...30 VDC (IO-Link)
Reverse polarity protection	Yes, to 0 V
Short-circuit proof	Yes
Consumption w/o load	≤100 mA (15 VDC)
Initializing time	≤ 300 ms after power on
Interpolation	Programmable
Output signals	A+, B+, R+, S+, S-/IO-Link
System accuracy	Typ. ±0.05° (+20 °C, EBS.R-2R092)
Sensing method	Magnetic
Status indicator	LED green/red
Interference immunity	DIN EN 61000-6-2
Emitted interference	DIN EN 61000-6-4
Approval	CE UL

### Technical data - electrical ratings (square-wave)

Pulses per revolution	1024 (1 ... 65536 programmable)
Phase shift	90 ° ±20°
Duty cycle	45...55 %
Reference signal	Zero pulse, width 90° Zero pulse, width 180° (programmable)
Output frequency	≤500 kHz
Output stages	HTL/TTL (Vin = Vout) TTL (programmable) IO-Link

### Technical data - electrical ratings (IO-Link)

IO-Link version	1.1
Device profile	Identification and diagnosis
IO-Link port type	Class A
Baud rate	230.4 kBaud (COM 3)
Cycle time	≥ 1 ms
Process data length	72 Bit

### Technical data - electrical ratings (IO-Link)

Process data structure	Bit 0 = SSC1 (speed monitor) Bit 1 = SSC2 (direction monitor) Bit 2 = quality Bit 3 = alarm Bit 4 = SSC3 (standstill monitor) Bit 7 = condition monitoring Bit 8-39 = 32 Bit Position Bit 40-71 = 32 Bit Speed
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### Additional data

Signal quality value
Working distance (airgap)
Device temperature
Device status
Statistic data
Adjustable parameters
User data (3 x 32 Byte)
Interpolation settings
Speed filter
Condition monitoring
Motion monitor settings
Digital switch output settings

### Technical data - mechanical design

Shaft type	ø8...48 mm (through hollow shaft)
Dimensions W x H x L	23 x 11 x 50 mm
Protection EN 60529	IP 66 IP 67
Operating speed	≤10000 rpm (EBS.R-2R092)
Working distance	0.1 ... 1.0 mm (radial air gap) ± 0.6 mm (axial misalignment)
Material	Housing: polyamide
Operating temperature	-40...+95 °C
Relative humidity	EN 60068-2-30:2005 95 % condensation permitted
Resistance	EN 60068-2-6 Vibration 30 g, 10-2000 Hz EN 60068-2-27 Shock 500 g, 1 ms
Pitch	2 mm (nominal)
Weight approx.	30 g
Connection	Flylead connector M12, 8-pin, length 0.3 m

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## General information

EB260F.IR-2R052 sensors are compatible with EBS.R-2R052 magnetic rotors and EB260F.IR-2R092 sensors are compatible with EBS.R-2R092 magnetic rotors, which needs to be ordered separately.

## Terminal assignment

### Connector M12 a-coded, 8-pin, male

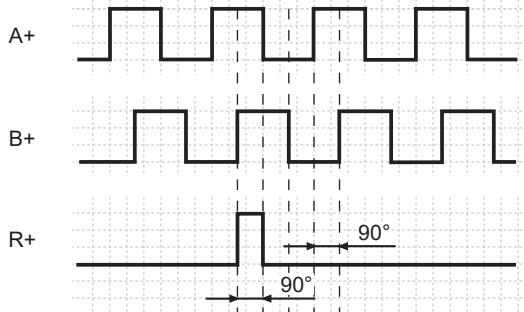
Pin	Assignment	Description
1	0 V	Voltage supply
2	+Vs	Voltage supply
3	A+	Output A
4	S+	Output S
5	B+	Output B
6	R+	Output R
7	S+/IO-Link	Output S (IO-Link)
8	+Vs2	Voltage supply (Output S+/IO-Link)



## Output signals

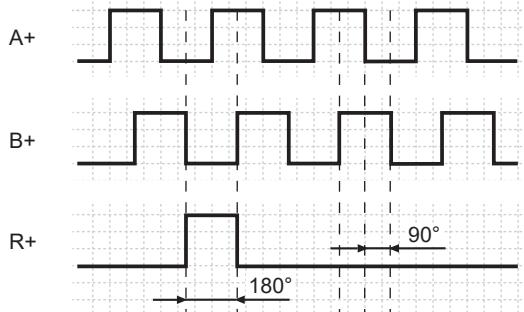
### HTL/TTL

Zero pulse electrical 90° A&B high at clockwise (CW) rotation (default)



### HTL/TTL

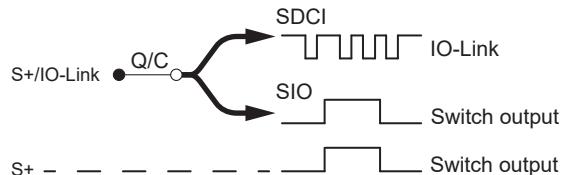
Zero pulse electrical 180° B low at clockwise (CW) rotation



## Output signals

### Output S

Output S is IO-Link capable and the following functions are parametrizable (SIO): Speed-, Standstill-, Direction-, Condition-, Alarm- or Quality-Monitor (default):



## Trigger level

### Outputs

HTL/push-pull short-circuit proof

Output level High  $\geq +Vs - 2\text{ V}$

Output level Low  $\leq 2\text{ V}$

Load  $\leq 30\text{ mA}$

### Outputs

TTL/RS422

Output level High  $\geq 2.5\text{ V}$

Output level Low  $\leq 0.5\text{ V}$

Load  $\leq 20\text{ mA}$

By default, the switching levels of the outputs A+, B+, R+ and S+ depend on the supply voltage +Vs: HTL/push-pull ( $+Vs = 10\ldots30\text{ VDC}$ ) or TTL/RS422 ( $+Vs = 4.5\ldots5.5\text{ VDC}$ ). Switching levels TTL/RS422 for  $+Vs = 4.5\ldots30\text{ VDC}$  can be parameterized.

The switching levels of the S+/IO-Link output depend on the supply voltage +Vs2: HTL/push-pull ( $+Vs2 = 10\ldots30\text{ VDC}$ ) or TTL/RS422 ( $+Vs2 = 4.5\ldots5.5\text{ VDC}$ ). If +Vs2 is not connected, the output is at TTL/RS422 level.

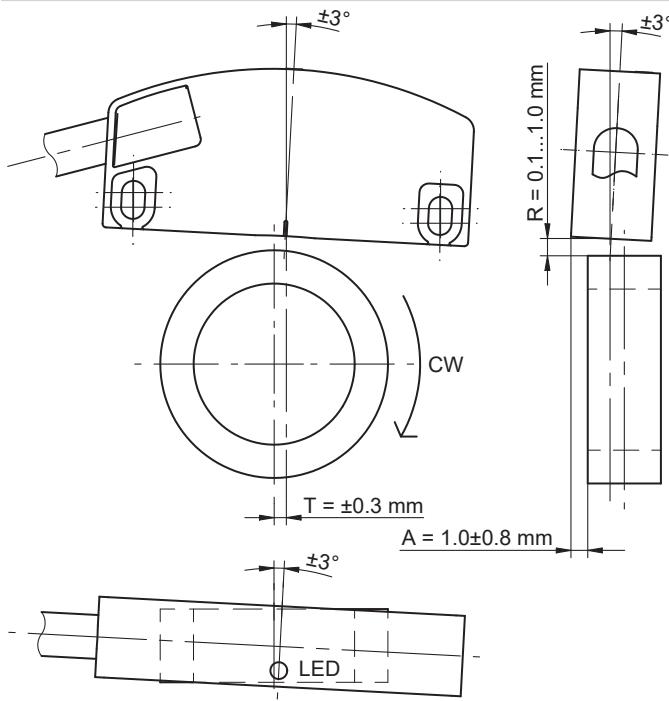
When using IO-Link, a power supply (+Vs2) of  $18\ldots30\text{ VDC}$  is required.

# EB260F.IR-2R092.VUMJN.01024L

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## Working distance



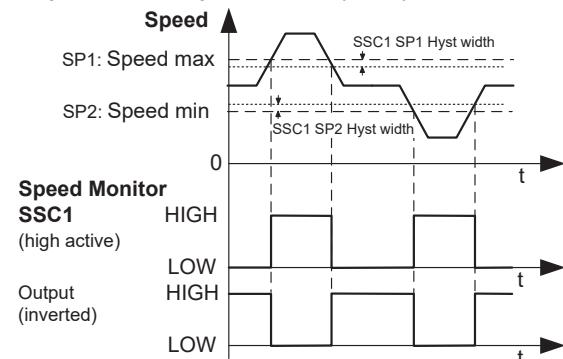
# EB260F.IR-2R092.VUMJN.01024L

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## Output Functions

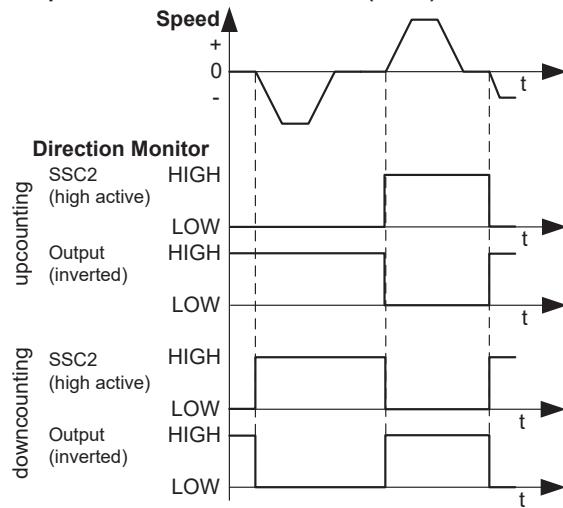
### Output function: Speed Monitor (SSC1)



#### Parameters:

- Switching points (Speed limit max, Speed limit min)
  - Switching logic (high active, low active)
  - Switching mode (Speed limit, Speed Window)
  - Switching hysteresis (Setpoint 1, Setpoint 2)
  - Output function
  - Output logic
  - Output startup settings
- For more details, please refer to the IODD.

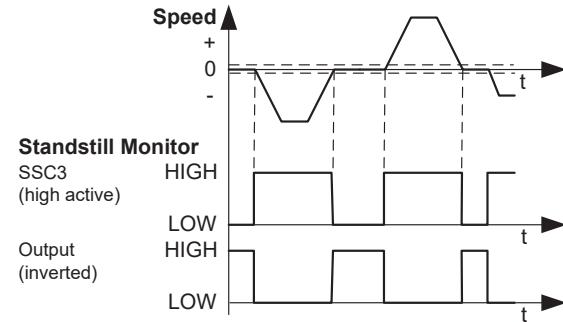
### Output function: Direction Monitor (SSC2)



#### Parameters:

- Switching point (Monitoring Direction)
  - Switching logic (high active, low active)
  - Switching hysteresis
  - Output function
  - Output logic
  - Output startup settings
- For more details, please refer to the IODD.

### Output function: Standstill Monitor (SSC3)



#### Parameters:

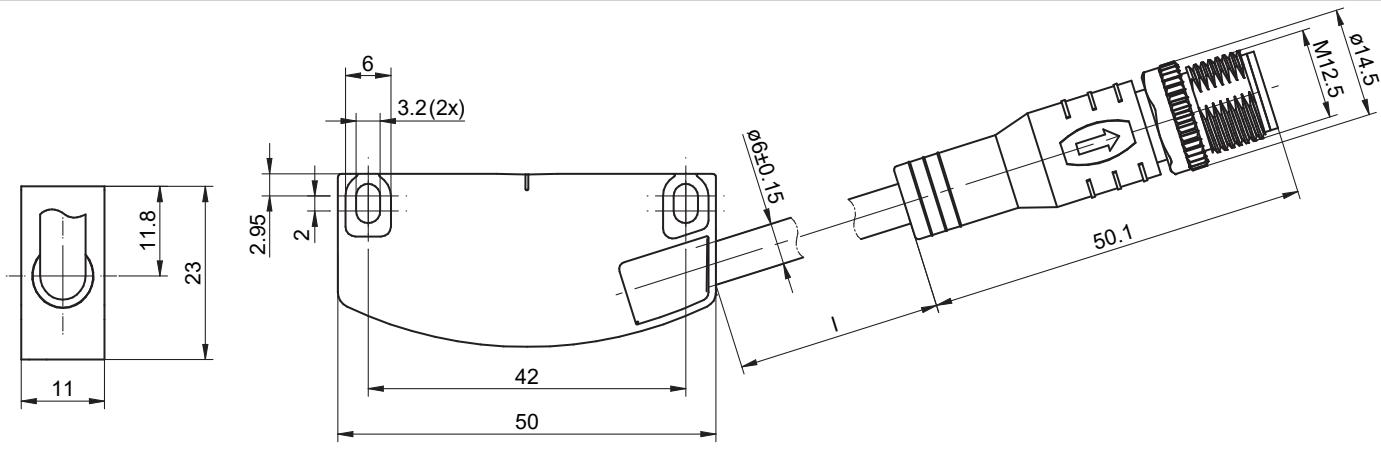
- Switching point (Standstill threshold)
  - Switching logic (high active, low active)
  - Switching hysteresis (Standstill threshold)
  - Output function
  - Output logic
  - Output startup settings
- For more details, please refer to the IODD.

# EB260F.IR-2R092.VUMJN.01024L

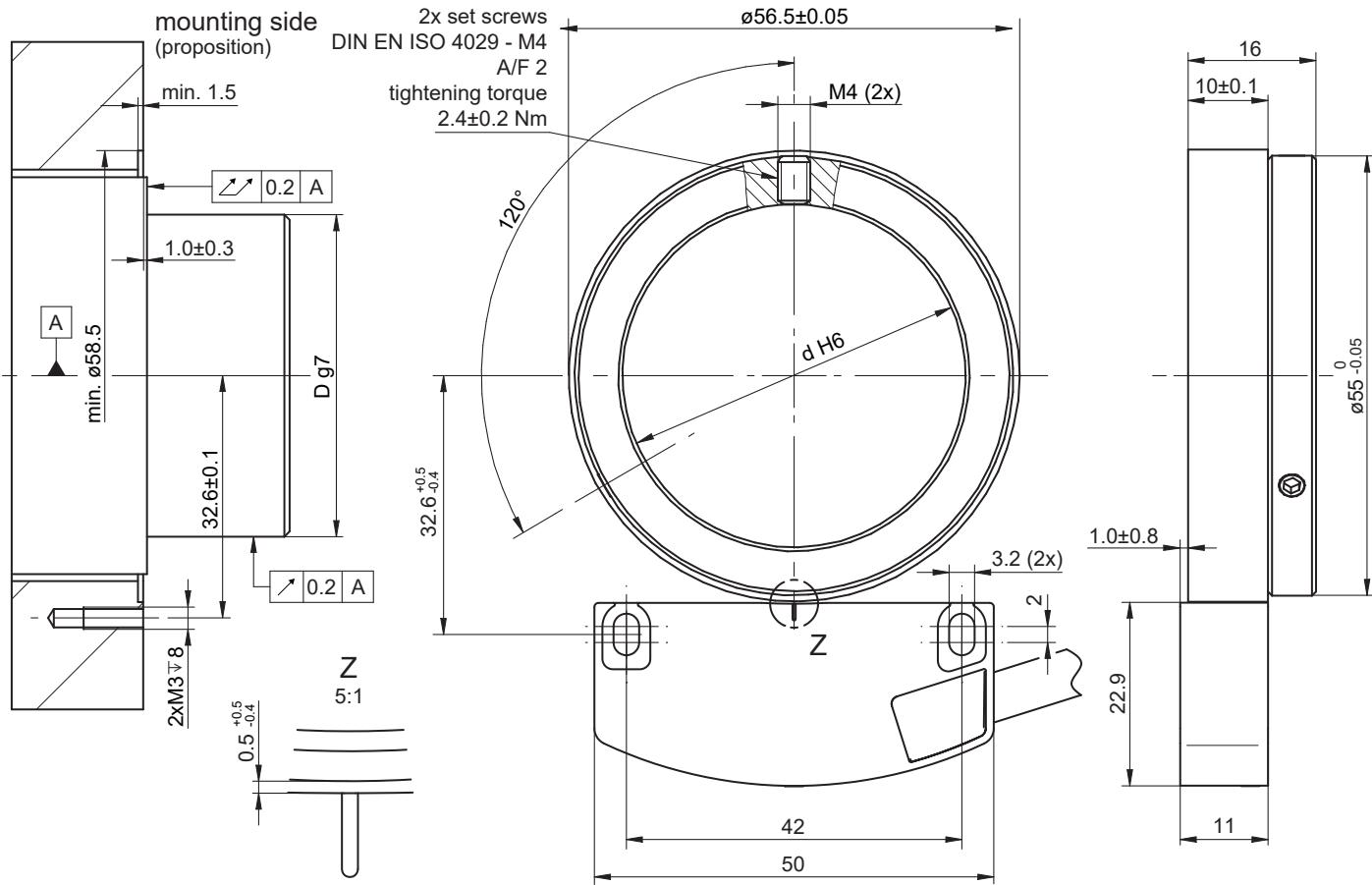
Programmable incremental encoder with zero pulse + IO-Link for condition monitoring

Article number: 11732179

## Dimensions



EB260F.IR-2R with connector M12



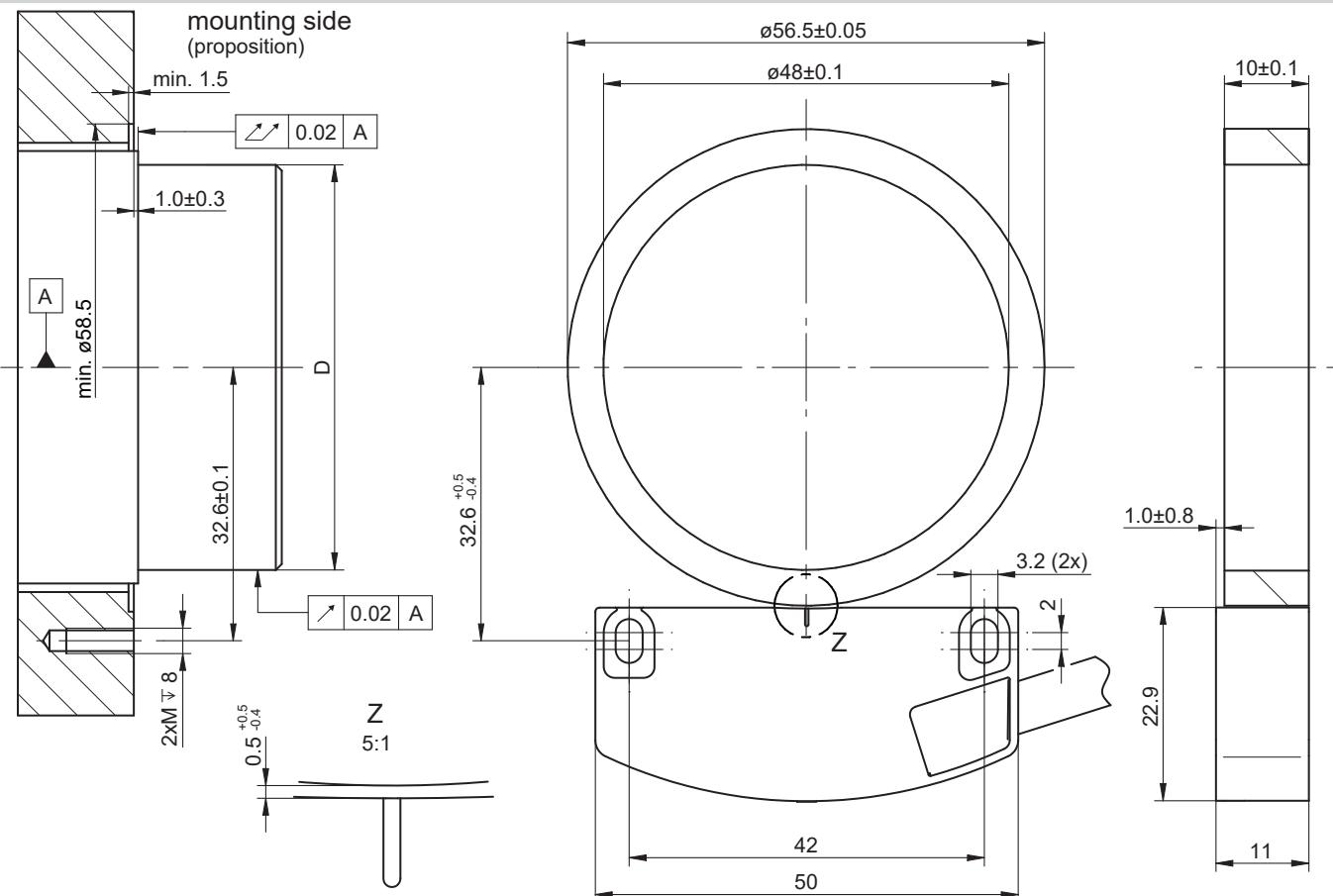
EB260F.IR-2R with EBS.R-2R092.S for screw mounting

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Article number: 11732179

## Dimensions



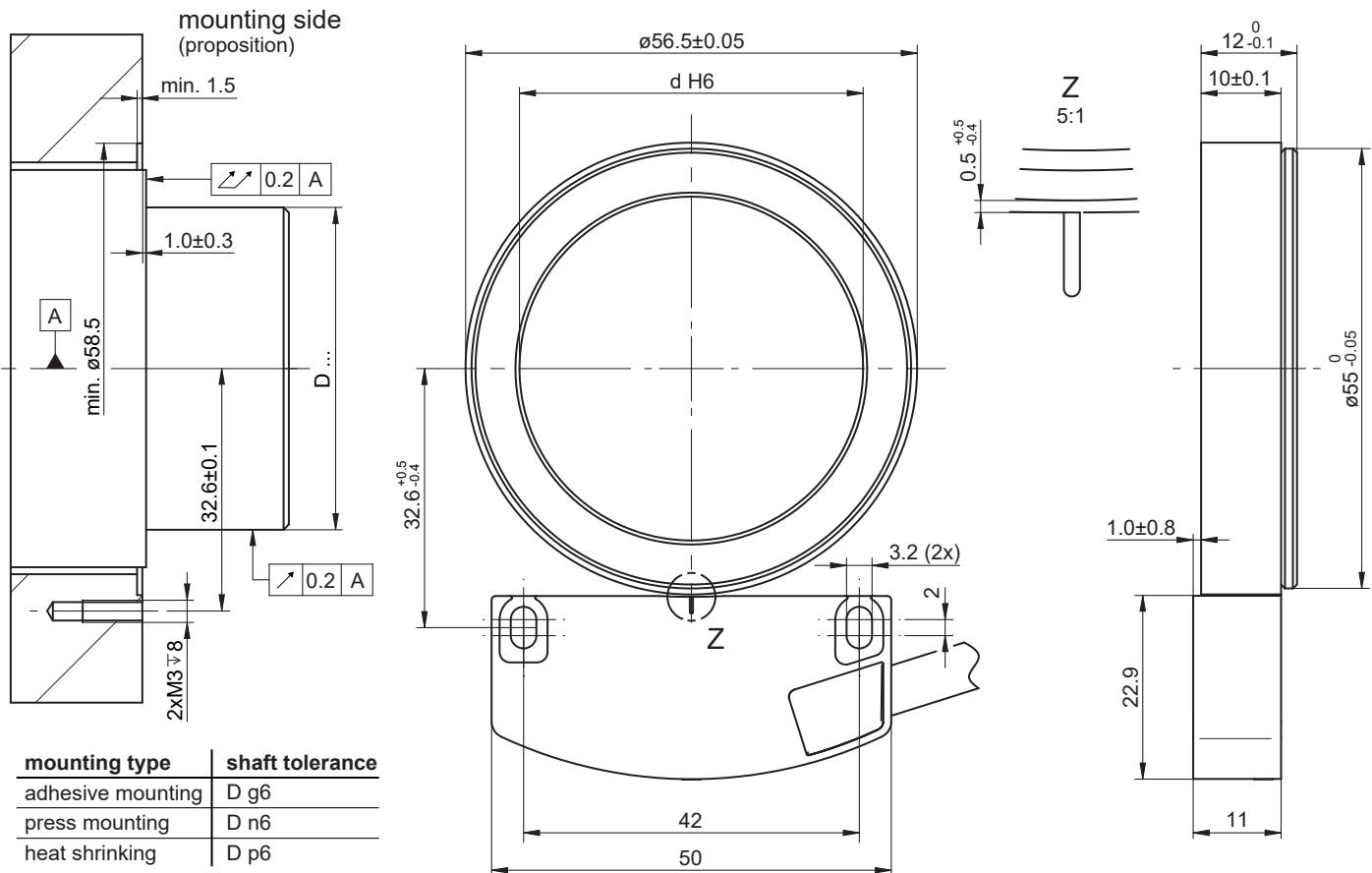
EB260F.IR-2R with EBS.R-2R092.B for bonding

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## Dimensions



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**Article number**

Sensor

Article number	Typecode	Description
11732178	EB260F.IR-2R052.VUMJN.01024L	HTL/TTL single-ended + IO-Link, Flylead connector M12, 8-pin, matches rotor 2R052
11732179	EB260F.IR-2R092.VUMJN.01024L	HTL/TTL single-ended + IO-Link, Flylead connector M12, 8-pin, matches rotor 2R092

**Magnetic rotor (accessory, needs to be ordered separately)**

Article number	Typecode	Description
11728677	EBS.R-2R052.S012.A16.H0031	2 mm pitch with reference track, 52 poles, screw mounting, ID=12 mm, OD=31.1 mm
11728693	EBS.R-2R052.S014.A16.H0031	2 mm pitch with reference track, 52 poles, screw mounting, ID=14 mm, OD=31.1 mm
11728694	EBS.R-2R092.S025.A16.H0057	2 mm pitch with reference track, 92 poles, screw mounting, ID=25 mm, OD=56.5 mm
11724909	EBS.R-2R052.B022.N10.H0031	2 mm pitch with reference track, 52 poles, for bonding, ID=22 mm, OD=31.1 mm
11724877	EBS.R-2R092.B048.N10.H0057	2 mm pitch with reference track, 92 poles, for bonding, ID=48 mm, OD=56.5 mm
11728698	EBS.R-2R052.U012.S12.H0031	2 mm pitch with reference track, 52 poles, for bonding/pressing/heat shrinking, ID=12 mm, OD=31.1 mm
11728701	EBS.R-2R052.U012.S12.H0031	2 mm pitch with reference track, 52 poles, for bonding/pressing/heat shrinking, ID=14 mm, OD=31.1 mm
11728702	EBS.R-2R092.U025.S12.H0057	2 mm pitch with reference track, 92 poles, for bonding/pressing/heat shrinking, ID=25 mm, OD=56.5 mm

**Accessories**
**Programming accessories**

11234828	USB-C IO-Link Master
11273351	CAM12.A8Z-11273351